

16. Session: Matrices and Vectors

Def.: An $m \times n$ -matrix A is a rectangular array of real numbers with m rows and n columns.

Ex.

$$A = \begin{bmatrix} 7 & 2 \\ 5 & 0 \\ -1 & 11 \end{bmatrix} \quad 3 \times 2\text{-matrix}$$

$$\begin{bmatrix} 8 & 0 & 7 \\ 5 & -1 & 10 \\ 2 & \sqrt{5} & 7 \end{bmatrix} \quad 3 \times 3\text{-matrix}$$

$$\begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad 2 \times 1\text{-matrix}$$

Def.: The number in the i^{th} row and j^{th} column of A is called the (i, j) -entry and denoted a_{ij} or $[A]_{ij}$.

Ex.

$$A = \begin{matrix} & \begin{matrix} 1 & 2 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 7 & 2 \\ 5 & 0 \\ -1 & 11 \end{bmatrix} \end{matrix}$$

$$[A]_{11} = 7, \quad [A]_{12} = 2$$

$$[A]_{21} = 5, \quad [A]_{22} = 0$$

$$[A]_{31} = -1, \quad [A]_{32} = 11$$

Def.: Let A and B be $m \times n$ -matrices and let c be a scalar*. Then $A+B$, $A-B$ and cA are the $m \times n$ -matrices with entries as follows:

$$[A+B]_{ij} = [A]_{ij} + [B]_{ij},$$

$$[A-B]_{ij} = [A]_{ij} - [B]_{ij},$$

$$[cA]_{ij} = c[A]_{ij},$$

for $i=1, 2, 3, \dots, m$ and $j=1, 2, 3, \dots, n$. The zero-matrix O is the $m \times n$ -matrix with $[O]_{ij} = 0$ for every i and j .

* "Scalar" means real number

Ex.

$$\begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix} + \begin{bmatrix} -4 & 1 & 0 \\ 5 & -6 & 1 \end{bmatrix} = \begin{bmatrix} 3+(-4) & 4+1 & 2+0 \\ 2+5 & -3+(-6) & 0+1 \end{bmatrix} = \begin{bmatrix} -1 & 5 & 2 \\ 7 & -9 & 1 \end{bmatrix},$$

$$\begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix} - \begin{bmatrix} -4 & 1 & 0 \\ 5 & -6 & 1 \end{bmatrix} = \begin{bmatrix} 3-(-4) & 4-1 & 2-0 \\ 2-5 & -3-(-6) & 0-1 \end{bmatrix} = \begin{bmatrix} 7 & 3 & 2 \\ -3 & 3 & -1 \end{bmatrix},$$

$$3 \cdot \begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix} = \begin{bmatrix} 3 \cdot 3 & 3 \cdot 4 & 3 \cdot 2 \\ 3 \cdot 2 & 3 \cdot (-3) & 3 \cdot 0 \end{bmatrix} = \begin{bmatrix} 9 & 12 & 6 \\ 6 & -9 & 0 \end{bmatrix}.$$

Theorem: Let A, B, C be $m \times n$ -matrices and let s, t be scalars. Then

(1) $A + B = B + A$

(2) $(A + B) + C = A + (B + C)$

(3) $A + 0 = A$

(4) $A - A = 0$

(5) $(st)A = s(tA)$

(6) $s(A + B) = sA + sB$

(7) $(s+t)A = sA + tA$.

Proof of (1): Both sides are $m \times n$ -matrices, and $[A+B]_{ij} = [A]_{ij} + [B]_{ij} = [B]_{ij} + [A]_{ij} = [B+A]_{ij}$, q.e.d.

Def.: Let A be an $m \times n$ -matrix. The transpose of A is the $n \times m$ -matrix A^T with

$$[A^T]_{ij} = [A]_{ji}$$

for $i = 1, 2, \dots, n$ and $j = 1, 2, \dots, m$.

Note: The columns of A^T are the rows of A and vice versa.

Ex. $\begin{bmatrix} 3 & 4 & 2 \\ 2 & -3 & 0 \end{bmatrix}^T = \begin{bmatrix} 3 & 2 \\ 4 & -3 \\ 2 & 0 \end{bmatrix},$

$$\begin{bmatrix} 1 & 7 \\ -2 & 0 \end{bmatrix}^T = \begin{bmatrix} 1 & -2 \\ 7 & 0 \end{bmatrix},$$

$$\begin{bmatrix} 5 \\ -3 \end{bmatrix}^T = [5 \quad -3].$$

Theorem: Let A and B be $m \times n$ -matrices, and let s be a scalar. Then

$$(1) (A+B)^T = A^T + B^T$$

$$(2) (sA)^T = s(A^T)$$

$$(3) (A^T)^T = A.$$

Def. An $1 \times n$ -matrix is called a row vector.

An $m \times 1$ -matrix is called a column vector.

Ex. $[5 \ 0 \ -1]$ row vector

$\begin{bmatrix} 2 \\ 7 \end{bmatrix}$ column vector

Note: We usually work with column vectors.

Ex.

$$\begin{bmatrix} 2 \\ 7 \end{bmatrix} + \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2+(-1) \\ 7+3 \end{bmatrix} = \begin{bmatrix} 1 \\ 10 \end{bmatrix},$$

$$5 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 5 \cdot 1 \\ 5 \cdot 3 \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \end{bmatrix}.$$

Def. A linear combination of the $m \times 1$ -vectors

$\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k$ is a vector of the form

$$c_1 \vec{u}_1 + c_2 \vec{u}_2 + \dots + c_k \vec{u}_k,$$

where c_1, c_2, \dots, c_k are scalars. These scalars are called the coefficients or weights of the linear combination.

Ex.

$$1 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \cdot \begin{bmatrix} 1 \\ 3 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ -1 \end{bmatrix} =$$

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 6 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 8 \end{bmatrix}$$

Thus, $\begin{bmatrix} 2 \\ 8 \end{bmatrix}$ is a linear combination of the vectors

$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$.

Ex. Is $\begin{bmatrix} 4 \\ -1 \end{bmatrix}$ a linear combination of $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$?

$$x \begin{bmatrix} 2 \\ 3 \end{bmatrix} + y \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 2x+3y \\ 3x+y \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix} \Leftrightarrow \begin{cases} 2x+3y=4 \\ 3x+y=-1 \end{cases} \Leftrightarrow$$

$$\begin{cases} 2x+3y=4 \\ y=-3x-1 \end{cases} \Leftrightarrow \begin{cases} 2x+3(-3x-1)=4 \\ y=-3x-1 \end{cases} \Leftrightarrow \begin{cases} -7x=7 \\ y=-3x-1 \end{cases} \Leftrightarrow \begin{cases} x=-1 \\ y=2 \end{cases}$$

Yes, $(-1) \begin{bmatrix} 2 \\ 3 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$.

Notation: The set of column vectors with m coordinates is denoted \mathbb{R}^m . Thus, a vector \vec{v} in \mathbb{R}^m has the form

$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}.$$

Def. The standard basis vectors in \mathbb{R}^m are

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \quad \dots, \quad \vec{e}_m = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

Ex. Standard basis vectors in \mathbb{R}^2 :

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \vec{i}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \vec{j}.$$

Ex. Standard basis vectors in \mathbb{R}^3 :

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \vec{i}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \vec{j}, \quad \vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \vec{k}.$$

Note that

$$\begin{bmatrix} x \\ y \end{bmatrix} = x\vec{i} + y\vec{j},$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = x\vec{i} + y\vec{j} + z\vec{k},$$

$$\vec{v} = v_1\vec{e}_1 + v_2\vec{e}_2 + \dots + v_m\vec{e}_m.$$