

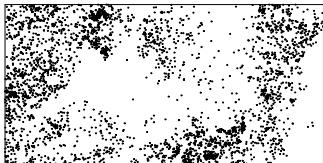
Two-step estimation for inhomogeneous spatial point processes

Rasmus Waagepetersen
Department of Mathematics
Aalborg University
Denmark

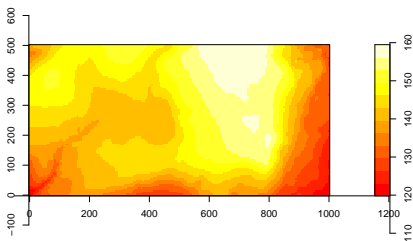
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Tropical rain forests trees

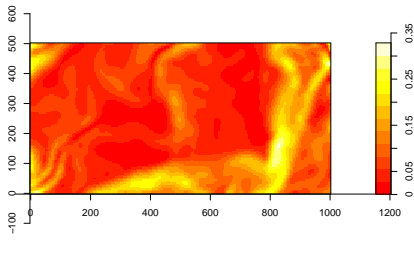
Beilschmiedia



- ▶ *observation window*
= 1000 m × 500 m
- ▶ seed dispersal ⇒ *clustering*
- ▶ *covariates* ⇒ *inhomogeneity*



Elevation



Norm of elevation gradient
(slope)

Intensity function and product density

Intensity function of point process \mathbf{X} on \mathbb{R}^2 :

$$\rho(u)dA \approx P(\mathbf{X} \text{ has a point in } A)$$

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Pair correlation and K -function (provided $g(u, v) = g(u - v)$)

$$g(u, v) = \frac{\rho^{(2)}(u, v)}{\rho(u)\rho(v)} \quad \text{and} \quad K(t) = \int_{\mathbb{R}^2} \mathbf{1}[\|u\| \leq t]g(u)du$$

NB: for Poisson process, $g(u - v) = 1$, clustering: $g(u - v) > 1$.

Parametric models

Study influence of covariates using log-linear model for intensity function:

$$\rho(u; \beta) = \exp(z(u)\beta^T)$$

and quantify clustering using parameter ψ in parametric model

$$K(t; \psi) = \int_{\|v\| \leq t} g(v; \psi) dv$$

for K/g -function.

Estimating function for β

Maximum likelihood estimation only easy in case of a Poisson process \mathbf{X} in which case log likelihood is

$$l(\beta) = \sum_{u \in \mathbf{X} \cap W} z(u) \beta^T - \int_W \rho(u; \beta) du$$

Poisson score estimating function based on point process \mathbf{X} observed in W :

$$u_1(\beta) = \sum_{u \in \mathbf{X} \cap W} z(u) - \int_W z(u) \rho(u; \beta) du$$

also applicable for *non-Poisson* point processes with intensity function $\rho(\cdot; \beta)$ (Schoenberg, 2004, Waagepetersen, 2007)

Estimating function for ψ

Estimate of K -function:

$$\hat{K}_\beta(t) = \sum_{u,v \in \mathbf{X} \cap W} \frac{1[0 < \|u - v\| \leq t]}{\rho(u; \beta)\rho(v; \beta)|W \cap W_{u-v}|}$$

Unbiased if $\beta = \beta^*$ 'true' regression parameter.

Minimum contrast estimation: minimize

$$\int_0^r (\hat{K}_\beta(t) - K(t; \psi))^2 dt$$

or solve estimating equation

$$u_{2,\beta}(\psi) = |W| \int_0^r (\hat{K}_\beta(t) - K(t; \psi)) \frac{dK(t; \psi)}{d\psi} dt = 0$$

Two-step estimation

Estimate $(\hat{\beta}, \hat{\psi})$ by solving

1. $u_1(\beta) = 0$
2. $u_{2,\hat{\beta}}(\psi) = 0$

or equivalently solve

$$u(\beta, \psi) = (u_1(\beta), u_{2,\beta}(\psi)) = 0.$$

Waagepetersen and Guan (2007): asymptotic properties of $(\hat{\beta}, \hat{\psi})$.

CLT for estimating function

Consider increasing observation windows W_n .

Divide \mathbb{R}^2 into quadratic cells $A_{ij} = s[i, i + 1[\times s[j, j + 1[$ of area s^2 .

Express Poisson score in terms of lattice process X_{ij} , $i, j \in \mathbb{Z}$:

$$u_1^n(\beta) = \sum_{u \in \mathbf{X} \cap W_n} z(u) - \int_{W_n} z(u) \rho(u; \beta) du =$$
$$\sum_{i,j} \left[\sum_{u \in \mathbf{X} \cap W_n \cap A_{ij}} z(u) - \int_{W_n \cap A_{ij}} z(u) \rho(u; \beta) du \right] = \sum_{ij: A_{ij} \subseteq W_n} X_{ij} + o_P(1)$$

Similarly:

$$u_{2,\beta}^n(\psi) = |W_n| \int_0^r (\hat{K}_\beta(t) - K(t; \psi)) \frac{dK(t; \psi)}{d\psi} dt = \sum_{ij: A_{ij} \subseteq W_n} Y_{ij} + o_P(1)$$

where

$$Y_{ij} = \int_0^r s^2 (\hat{K}_{\beta,ij}(t) - K(t; \psi)) \frac{dK(t; \psi)}{d\psi} dt$$

and

$$\hat{K}_{\beta,ij}(t) = \frac{1}{s^2} \sum_{u \in \mathbf{X} \cap A_{ij}, v \in \mathbf{X}} \frac{1[0 < \|u - v\| \leq t]}{\rho(u; \beta) \rho(v; \beta)}$$

estimate of K -function based on $\mathbf{X} \cap A_{ij} \oplus r$.

Apply Guyon/Bolthausen CLT for mixing lattice processes to random field $\{Z_{ij}\}_{ij}$ of linear combinations

$$Z_{ij} = X_{ij}x^T + Y_{ij}y^T.$$

Use result in Aitchison and Silvey (1958) to show that there exist $O_P(|W_n|^{-1/2})$ consistent sequences of solutions $\hat{\beta}_n$ and $\hat{\psi}_n$ of $u_1^n(\beta) = 0$ and $u_{2,\hat{\beta}_n}^n(\psi) = 0$.

Finally, Taylor expansion:

$$|W_n|^{-1/2} u^n(\beta^*, \psi^*) = |W_n|^{1/2} [(\hat{\beta}_n, \hat{\psi}_n) - (\beta^*, \psi^*)] \frac{J_n(\tilde{\beta}, \tilde{\psi})}{|W_n|}$$

where

$$J_n(\beta, \psi) = \begin{bmatrix} \frac{d}{d\beta^T} u_{n,1}(\beta) & \frac{d}{d\beta^T} u_{n,2}(\beta, \psi) \\ 0 & \frac{d}{d\psi^T} u_{n,2}(\beta, \psi) \end{bmatrix}$$

and $\frac{J_n(\tilde{\beta}, \tilde{\psi})}{|W_n|} - I_n \rightarrow 0$ for non-random matrices I_n . Hence

$$|W_n|^{1/2} [(\hat{\beta}_n, \hat{\psi}_n) - (\beta^*, \psi^*)] I_n \Sigma_n^{-1/2} \rightarrow N(0, I)$$

where Σ_n variance matrix for $|W_n|^{-1/2} u^n(\beta^*, \psi^*)$.

Mixing

Consider $E_1, E_2 \subseteq \mathbb{R}^2$ point configurations F_1 and F_2 .

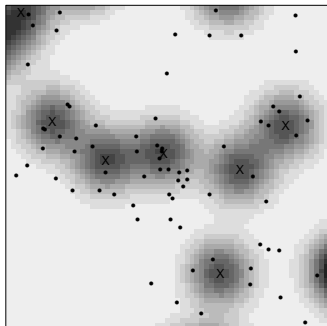
Need polynomial decay of

$$|P(\mathbf{X} \cap E_1 \in F_1, \mathbf{X} \cap E_2 \in F_2) - P(\mathbf{X} \cap E_1 \in F_1)P(\mathbf{X} \cap E_2 \in F_2)|$$

as function of distance between E_1 and E_2 .

This can easily be verified for a Poisson cluster process where cluster density decays fast enough.

Example: modified Thomas process



Mothers (crosses) stationary Poisson point process \mathbf{M} with intensity $\kappa > 0$.

Clusters $\mathbf{X}_m, m \in \mathbf{M}$ Poisson processes of offspring dispersed according to $k =$ bivariate isotropic Gaussian density.

ω : standard deviation of Gaussian density

α : Expected number of offspring for each mother.

Cox process with random intensity function:

$$\Lambda(u) = \alpha \sum_{m \in \mathbf{M}} k(u - m; \omega)$$

Inhomogeneous Thomas process

$z_{1:p}(u) = (z_1(u), \dots, z_p(u))$ vector of p nonconstant covariates.

$\beta_{1:p} = (\beta_1, \dots, \beta_p)$ regression parameter.

Inhomogeneous random intensity function:

$$\Lambda_{\text{inhom}}(u) = \exp(z(u)_{1:p} \beta_{1:p}^T) \Lambda(u)$$

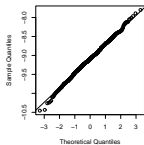
$$\rho(u; \beta) = \exp(z(u) \beta^T) \quad \beta = (\beta_0, \beta_1, \dots, \beta_p) = (\log \kappa \alpha, \beta_1, \dots, \beta_p)$$
$$\psi = (\kappa, \omega)$$

Thomas process mixing and inhomogeneous Thomas process
independent thinning of Thomas \Rightarrow inhomogeneous Thomas
mixing too.

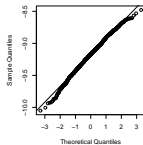
Simulations: $\log \hat{\kappa}$

QQ-plots with varying expected numbers of mothers/offspring.

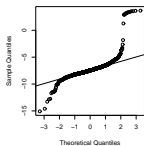
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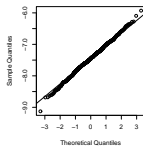
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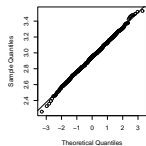
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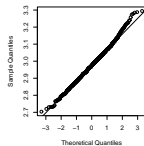
Simulations: $\log \hat{\omega}$

QQ-plots with varying expected numbers of mothers/offspring.

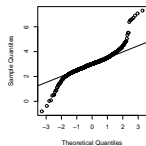
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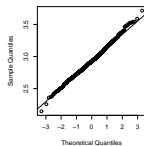
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Tropical trees

Estimates of κ and ω for model with altitude and gradient:
 8×10^{-5} and 20.

Estimates of κ and ω for model with altitude and gradient *and* soil variables nitrogen, phosphorous, potassium, pH: 2.2×10^{-4} and 13.

Hence much residual clustering explained by soil variables.

Confidence intervals: $[1.2 \times 10^{-4}, 3.9 \times 10^{-4}]$ and $[10,17]$.

Issues

- ▶ choice of integration limit r for minimum contrast estimation

$$\int_0^r (\hat{K}_{\hat{\beta}}(t) - K(t; \psi))^2 dt$$

- ▶ variance of $\hat{K}_{\hat{\beta}}(t)$ smaller than variance of $\hat{K}_{\beta^*}(t)$ hence better to use $\hat{\beta}$ than β^* when estimating ψ .
- ▶ LGCPs mixing if Gaussian field is mixing - but only mixing results for Gaussian lattice processes.
- ▶ two-step estimation only depends on first and second order properties - but when is a parametric model $K(\cdot; \psi)$ a legitimate K -function ?