

# Unbiased estimating functions for spatial point processes

Rasmus Waagepetersen  
Department of Mathematical Sciences  
Aalborg University

based on joint work (in progress !) with

Adrian Baddeley, Jean-Francois Coeurjolly, Yongtao Guan,  
Abdollah Jalilian and Ege Rubak

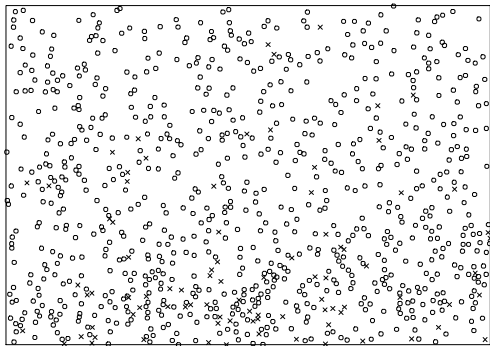
# Outline

- ▶ Data examples
- ▶ GNZ and Campbell formulae
- ▶ Gibbs and Cox spatial point processes
- ▶ pseudo-likelihood and composite likelihood
- ▶ Monte Carlo approximations and relation to logistic regression
- ▶ Examples of applications

Aim: discuss closely related estimating functions for two very distinct classes of point processes.

# Mucous membrane cells

Centres of cells in mucous membrane:



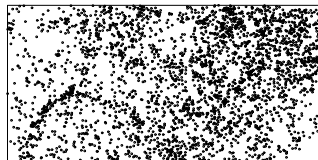
*Repulsion* due to physical extent of cells

*Inhomogeneity* - lower intensity in upper part

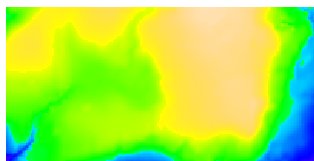
*Bivariate* - two types of cells

Same type of inhomogeneity for two types ?

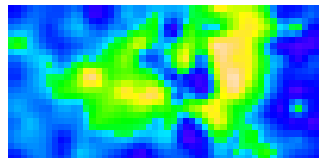
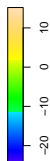
## Data example: *Capparis Frondosa*



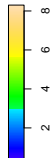
- ▶ observation window  $W$   
 $= 1000 \text{ m} \times 500 \text{ m}$
- ▶ seed dispersal  $\Rightarrow$  clustering
- ▶ environment  $\Rightarrow$  inhomogeneity



Elevation



Potassium content in soil.



Objective: quantify dependence on environmental variables.

## Intensity and conditional intensity

Point process  $\mathbf{X}$ : random point pattern. Assume observed in bounded window  $W \subset \mathbb{R}^2$ .  $u$  spatial location in  $W$ .

Intensity  $\lambda(u)$ : for infinitesimal region  $A$  and  $u \in A$ ,

$$P(\mathbf{X} \text{ point in } A) = \lambda(u)|A|$$

Conditional intensity  $\lambda(u, \mathbf{X})$ :

$$P(\mathbf{X} \text{ has a point in } A | \mathbf{X} \setminus A) = \lambda(u, \mathbf{X})|A|$$

Note

$$P(\mathbf{X} \text{ point in } A) = \mathbb{E}P(\mathbf{X} \text{ point in } A | \mathbf{X} \setminus A) \Rightarrow \lambda(u) = \mathbb{E}\lambda(u, \mathbf{X})$$

# GNZ and Campbell formulae

Georgii-Nguyen-Zessin formula:

$$\mathbb{E} \sum_{u \in \mathbf{X}} f(u, \mathbf{X} \setminus u) = \int_W \mathbb{E}[f(u, \mathbf{X}) \lambda(u, \mathbf{X})] du$$

for non-negative functions  $f$ .

Campbell formula:

$$\mathbb{E} \sum_{u \in \mathbf{X}} f(u) = \int_W f(u) \lambda(u) du$$

Note: special case of GNZ since  $\lambda(u) = \mathbb{E} \lambda(u, \mathbf{X})$ .

# Gibbs point processes

Gibbs point processes specified by explicit model for the conditional intensity.

Strauss:

$$\lambda_{\theta}(u, \mathbf{X}) = \exp[\beta + \psi n_R(u, \mathbf{X})], \quad \beta > 0, \psi \leq 0$$

$n_R(u, \mathbf{X})$ : number of neighboring points within distance  $R$  from  $u$ .

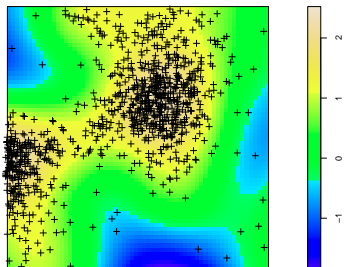
Inhomogeneous:  $Z(u)$  covariate at  $u \in \mathbb{R}^2$ .

$$\lambda_{\theta}(u, \mathbf{X}) = \exp[\beta Z(u)^T + \psi n_R(u, \mathbf{X})]$$

# Cox processes

**X** Poisson process with intensity function  $\lambda(\cdot)$ :

total number of points Poisson and given this, points *iid* with density  $\propto \lambda(u)$ .



**X** is a *Cox process* driven by the *random* intensity function  $\Lambda$  if, conditional on  $\Lambda = \lambda$ , **X** is a Poisson process with intensity function  $\lambda$ .

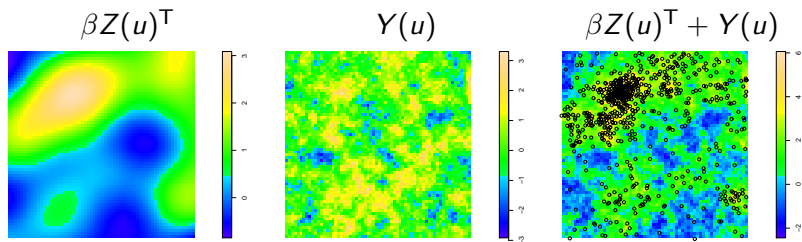


## Example: log Gaussian Cox process

log Gaussian Cox process (“point process GLMM”)

$$\Lambda(u) = \exp[\beta Z(u)^T + Y(u)]$$

where  $\{Y(u)\}$  Gaussian random field:



For Gibbs point process  $\lambda(u, \mathbf{X})$  is given but  $\lambda(u) = \mathbb{E}\lambda(u, \mathbf{X})$  hard.

For Cox process,  $\lambda(u, \mathbf{X})$  not known but

$$\lambda(u)|A| = P(\mathbf{X} \text{ point in } A) = \mathbb{E}P(\mathbf{X} \text{ point in } A|\Lambda) = \mathbb{E}\Lambda(u)|A|$$

Often  $\lambda(u) = \mathbb{E}\Lambda(u)$  easy to evaluate for Cox processes.

E.g.  $\log \Lambda(u) \sim N(\beta Z(u)^T, \sigma^2)$  [log Gaussian Cox process]:

$$\lambda(u) = \exp(\beta Z(u)^T + \sigma^2/2)$$

## Estimating function

Estimating function:  $e(\theta)$  [ $e(\theta, \mathbf{X})$ ] function of  $\theta$  and data  $\mathbf{X}$ .

Parameter estimate  $\hat{\theta}$  solution of

$$e(\theta) = 0$$

Sensitivity:

$$S = -\mathbb{E}\left[\frac{d}{d\theta}e(\theta)\right]$$

minus expected derivative of  $e(\theta)$

## Estimating function

Estimating function:  $e(\theta)$  [ $e(\theta, \mathbf{X})$ ] function of  $\theta$  and data  $\mathbf{X}$ .

Parameter estimate  $\hat{\theta}$  solution of

$$e(\theta) = 0$$

Sensitivity:

$$S = -\mathbb{E}\left[\frac{d}{d\theta}e(\theta)\right]$$

minus expected derivative of  $e(\theta)$

$\hat{\theta}$  unbiased  $\mathbb{E}\hat{\theta} = \theta^*$  if  $e(\theta)$  unbiased  $\mathbb{E}e(\theta^*) = 0$  ( $\theta^*$  true value).

$$\text{Var}\hat{\theta} = S^{-1}\Sigma S^{-1} \quad \Sigma = \text{Vare}(\theta^*)$$

How do we construct unbiased estimating functions involving  $\mathbf{X}$  and  $\theta$  ?

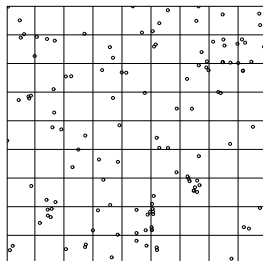
# Composite and pseudo-likelihood

Disjoint subdivision  $W = \cup_{i=1}^m C_i$  in  
'cells'  $C_i$ .

$u_i \in C_i$  'center' point.

Random indicator variables:

$N_i = 1[\mathbf{X} \text{ has a point in } C_i \neq \emptyset]$   
(presence/absence of points in  $C_i$ ).



$$P(N_i = 1) = |C_i| \lambda_{\theta}(u_i) \text{ and } P(N_i = 1 | \mathbf{X} \setminus C_i) = |C_i| \lambda_{\theta}(u_i, \mathbf{X})$$

Idea: form composite likelihoods based on  $N_i$  with marginal or conditional probabilities.

Consider limit when  $|C_i| \rightarrow 0$ .

Log composite likelihood (in fact log likelihood for Poisson):

$$\sum_{u \in \mathbf{X}} \log \lambda_{\theta}(u) - \int_W \lambda_{\theta}(u) du$$

Log pseudo-likelihood (Besag, 1977)

$$\sum_{u \in \mathbf{X}} \log \lambda_{\theta}(u, \mathbf{X} \setminus u) - \int_W \lambda_{\theta}(u, \mathbf{X}) du$$

Scores:

$$\sum_{u \in \mathbf{X}} \frac{\lambda'_{\theta}(u)}{\lambda_{\theta}(u)} - \int_W \lambda'_{\theta}(u) du$$

and

$$\sum_{u \in \mathbf{X}} \frac{\lambda'_{\theta}(u, \mathbf{X} \setminus u)}{\lambda_{\theta}(u, \mathbf{X} \setminus u)} - \int_W \lambda'_{\theta}(u, \mathbf{X}) du$$

unbiased estimating functions by Campbell/GNZ.

Issue:

- ▶ integrals

$$\int_W \lambda'_\theta(u) du \text{ and } \int_W \lambda'_\theta(u, \mathbf{X}) du$$

often not explicitly computable.

Numerical quadrature may introduce bias.

## Monte Carlo approximation

Let  $\mathbf{D}$  'quadrature/dummy' point process of intensity  $\rho(\cdot)$  and independent of  $\mathbf{X}$ .

By GNZ

$$\mathbb{E} \int_W \lambda'(u, \mathbf{X}) du = \mathbb{E} \sum_{u \in \mathbf{X} \cup \mathbf{D}} \frac{\lambda'(u, \mathbf{X})}{\lambda(u, \mathbf{X}) + \rho(u)}$$

By Campbell

$$\int_W \lambda'(u) du = \mathbb{E} \sum_{u \in \mathbf{X} \cup \mathbf{D}} \frac{\lambda'(u)}{\lambda(u) + \rho(u)}$$

Idea: replace integrals in pseudo- or composite likelihood with unbiased estimates using  $\mathbf{D}$ .



# Dummy point process

Should be easy to simulate and mathematically tractable.

Possibilities:

1. Poisson process
2. binomial point process (fixed number of independent points)
3. stratified binomial point process

Stratified:

.	+	+	+
+	+	+	+
+	+		+
+	+	+	+

# Monte Carlo approximation and logistic regression

Consider binary variables  $Y_u$  with

$$p(u) = P(Y_u = 1) = \frac{f_\theta(u)}{f_\theta(u) + 1}$$

Log logistic regression likelihood:

$$\begin{aligned} \sum_{u: Y_u=1} \log \frac{f_\theta(u)}{1 + f_\theta(u)} + \sum_{u: Y_u=0} \log \frac{1}{1 + f_\theta(u)} = \\ \sum_{u: Y_u=1} \log f_\theta(u) + \sum_{\text{all } u} \log \frac{1}{1 + f_\theta(u)} \end{aligned}$$

Score function:

$$\sum_{u: Y_u=1} \frac{f'_\theta(u)}{f_\theta(u)} + \sum_{\text{all } u} \frac{f'_\theta(u)}{1 + f_\theta(u)}$$

Approximate pseudo- and composite likelihood scores:

$$s(\theta) = \sum_{u \in \mathbf{X}} \frac{\lambda'_{\theta}(u, \mathbf{X} \setminus u)}{\lambda_{\theta}(u, \mathbf{X} \setminus u)} - \sum_{u \in (\mathbf{X} \cup \mathbf{D})} \frac{\lambda'_{\theta}(u, \mathbf{X} \setminus u)}{\lambda_{\theta}(u, \mathbf{X} \setminus u) + \rho(u)}$$

$$s(\theta) = \sum_{u \in \mathbf{X}} \frac{\lambda'_{\theta}(u)}{\lambda_{\theta}(u)} - \sum_{u \in (\mathbf{X} \cup \mathbf{D})} \frac{\lambda'_{\theta}(u)}{\lambda_{\theta}(u) + \rho(u)}$$

Note: of logistic regression/case control form with 'probabilities'

$$p(u|\mathbf{X}) = \frac{\lambda_{\theta}(u, \mathbf{X} \setminus u)}{\lambda_{\theta}(u, \mathbf{X} \setminus u) + \rho(u)}$$

and

$$p(u) = \frac{\lambda_{\theta}(u)}{\lambda_{\theta}(u) + \rho(u)}$$

I.e. probabilities that  $u \in \mathbf{X}$  given  $u \in \mathbf{X} \cup \mathbf{D}$ .

Hence computations straightforward with `glm()` software !

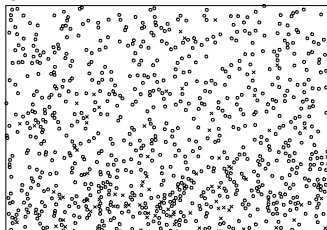
# Asymptotic results

Available - but quite technical (will skip details here).

Asymptotic covariance matrix implemented in spatstat  $\Rightarrow$  approximate confidence intervals.

Possible to evaluate the proportion of estimation variance due to random quadrature points.

## Example: mucous membrane



86 (type 1) + 807 (type 2) points.

$1 \times 0.7$  observation window.

Marked point  $u = (x, y, m)$  where  $m = 1$  or 2 (two types of points).

Bivariate Strauss point process with

$$\lambda_{\theta}(u, \mathbf{X}) = \exp[q_m(y) + \psi n_R(u, \mathbf{X})]$$

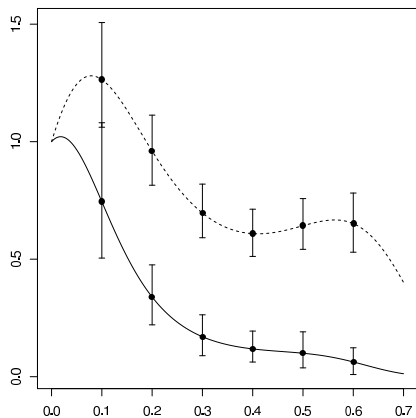
$q_m(y)$ : polynomial in spatial  $y$ -coordinate.

$n_R(u, \mathbf{X})$ : number of neighbors within range  $R = 0.008$ .

3600 stratified dummy points (random marks 1 or 2).

# Fitted polynomials

Fitted polynomials (with confidence intervals for selected  $y$  values):



Polynomials significantly different according to logistic likelihood ratio test (parametric bootstrap).

## Decomposition of variance

	3600				14400		
	$\hat{\theta}$	$\text{sd}(\hat{\theta})$	$\text{sd}(T_1)$	inc. (%)	$\text{sd}(\hat{\theta})$	$\text{sd}(T_1)$	inc. (%)
$q_1(0.1)$	6.004	0.195	0.189	3.608	0.191	0.189	0.812
$q_1(0.3)$	4.528	0.267	0.263	1.332	0.264	0.263	0.301
$q_1(0.5)$	3.994	0.406	0.404	0.555	0.404	0.404	0.146
$q_2(0.1)$	7.800	0.091	0.078	15.623	0.082	0.079	3.801
$q_2(0.3)$	7.204	0.083	0.075	10.923	0.076	0.075	2.589
$q_2(0.5)$	7.123	0.086	0.077	10.558	0.080	0.078	2.824
$\psi$	-2.594	0.344	0.341	0.971	0.342	0.341	0.197

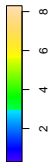
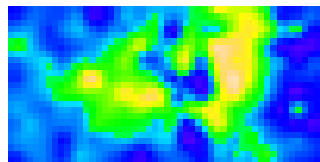
$\text{sd}(T_1) \approx$  standard deviation for pseudo-likelihood without approximation.

# Example: tree species *Capparis Frondosa* and *Loncocharpus Heptaphyllus*

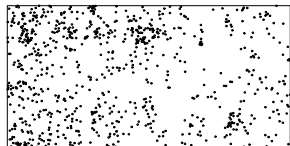
*Capparis Frondosa*



Potassium content in soil.



*Loncocharpus Heptaphyllus*



Covariates pH, elevation, gradient, potassium,...

Objective: infer regression model  $\lambda_{\beta}(u) = \exp[\beta Z(u)^T]$

Clustered point patterns: Cox point process natural model.



Problem: covariates sampled on (coarse) deterministic grid.

Plots shown: interpolated values of covariates.

Hence unbiased Monte Carlo approximation not applicable.

For now: integral

$$\int_W \lambda_\beta(u) du$$

approximated using numerical quadrature based on interpolated values.

Need to convince biologists to use random sampling designs.

# Optimality ?

Composite likelihood score

$$\sum_{u \in \mathbf{X}} \frac{\lambda'_{\beta}(u)}{\lambda_{\beta}(u)} - \int_{\mathcal{W}} \lambda'_{\beta}(u) du$$

optimal for Poisson (likelihood).

Which  $f$  makes

$$e_f(\beta) = \sum_{u \in \mathbf{X}} f(u) - \int_{\mathcal{W}} f(u) \lambda_{\beta}(u) du$$

optimal for Cox point process (positive dependence between points) ?

# Optimal first-order estimating equation

Optimal choice of  $f$ : smallest variance

$$\text{Var}\hat{\beta} = V_f = S_f^{-1}\Sigma_f S_f^{-1}$$

where

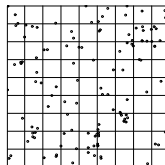
$$S_f = -\mathbb{E}\frac{d}{d\beta^T}e_f(\beta) \quad \Sigma_f = \text{Vare}_f(\beta)$$

Possible to obtain optimal  $f$  as solution of certain Fredholm integral equation.

Numerical solution of integral equation leads to estimating function of quasi-likelihood type.

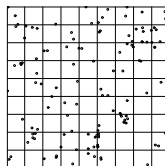
## Quasi-likelihood

Approximate solution of Fredholm integral equation using numerical quadrature: Riemann sum dividing  $W$  into cells  $C_j$  with representative points  $u_j$ .



## Quasi-likelihood

Approximate solution of Fredholm integral equation using numerical quadrature: Riemann sum dividing  $W$  into cells  $C_i$  with representative points  $u_j$ .



Resulting estimating function is *quasi-likelihood*

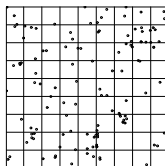
$$(N - \mu)V^{-1}D$$

based on

$$N = (N_1, \dots, N_m), \quad N_i = 1[\mathbf{X} \text{ has point in } C_i].$$

## Quasi-likelihood

Approximate solution of Fredholm integral equation using numerical quadrature: Riemann sum dividing  $W$  into cells  $C_i$  with representative points  $u_i$ .



Resulting estimating function is *quasi-likelihood*

$$(N - \mu)V^{-1}D$$

based on

$$N = (N_1, \dots, N_m), \quad N_i = 1[\mathbf{X} \text{ has point in } C_i].$$

$\mu$  mean of  $N$ :

$$\mu_i = \mathbb{E}N_i = \lambda_\beta(u_i)|C_i| \text{ and } D = [d\mu(u_i)/d\beta_l]_{il}$$

$V$  covariance of  $N$  (involves covariance of random intensity):

$$V_{ij} = \text{Cov}[N_i, N_j] = \mu_i 1[i = j] + \mu_i \mu_j \text{Cov}[\Lambda(u_i), \Lambda(u_j)]$$

## Results with composite likelihood and quasi-likelihood

species	$\hat{\beta}$
Loncocharpus	CL $-6.49 - 0.021N_{\min} - 0.11P - 0.59pH - 0.11twi$ (81.06*, 7.45*, 58.78, 282.89*, 53.19*) $\times 10^{-3}$
	QL $-6.49 - 0.023N_{\min} - 0.12P - 0.55pH - 0.084twi$ (80.15*, 6.95*, 55.23*, 266.10*, 45.47) $\times 10^{-3}$
Capparis	CL $-5.07 + 0.028ele - 1.10grad + 0.0043K$ (79.54*, 9.98*, 1200.36, 1.16*) $\times 10^{-3}$
	QL $-5.10 + 0.019ele - 2.50grad + 0.0039K$ (77.77*, 8.86*, 935.02*, 1.02*) $\times 10^{-3}$

Estimated standard errors always smallest for QL. Covariate grad significant according to QL but not for CL.

## References

Waagepetersen (2007). An estimating function approach to inference for inhomogeneous Neyman-Scott processes, *Biometrics*.

Waagepetersen, R. (2007). Estimating functions for inhomogeneous spatial point processes with incomplete covariate data, *Biometrika*.

Jalilian, Guan and Waagepetersen (2012). Decomposition of variance for spatial Cox processes, *Scandinavian Journal of Statistics*, to appear.

Guan, Jalilian and Waagepetersen (2012). Optimal first order estimating functions for spatial point processes, submitted.

Baddeley, Couerjolly, Rubak and Waagepetersen (2012). A logistic regression estimating function for spatial Gibbs point processes, in preparation.

Thanks for your attention !