# Maximum likelihood estimation for linear mixed models

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February 8, 2023

## Outline for today

- ▶ linear mixed models
- the likelihood function
- maximum likelihood estimation
- restricted maximum likelihood estimation

#### Linear mixed models

Consider mixed model:

$$Y_{ij} = \beta_1 + U_i + \beta_2 x_{ij} + \epsilon_{ij}$$

May be written in matrix vector form as

$$Y = X\beta + ZU + \epsilon$$

where 
$$\beta = (\beta_1, \beta_2)^T$$
,  $U = (U_1, \dots, U_k)^T$  and  $\epsilon = (\epsilon_{11}, \epsilon_{12}, \dots, \epsilon_{km})^T$ ,  $X$  is  $n \times 2$  and  $Z$  is  $n \times k$ .

## Linear mixed model: general form

Consider model

$$Y = X\beta + ZU + \epsilon$$

where  $U \sim N(0, \Psi)$  and  $\epsilon \sim N(0, \Sigma)$  are independent.

All previous models special cases of this.

Then Y has multivariate normal distribution

$$Y \sim N(X\beta, Z\Psi Z^{\mathsf{T}} + \Sigma)$$

#### Hierarchical version

- 1.  $U \sim N(0, \Psi)$
- 2.  $Y|U = u \sim N(X\beta + Zu, \Sigma)$

Useful for generalization to generalized linear mixed models.

**Ex**: Poisson log-normal:

Given U = u,  $Y_i$  independent with  $Y_i \sim Poisson(\lambda_i)$  where  $\lambda_i = \exp(\eta_i)$  and  $\eta = X\beta + Zu$ .

Note likelihood (marginal density of Y) typically not of simple form in case of generalized linear mixed models.

#### Some useful matrix identities

Woodbury identity:

$$(A + BCD)^{-1} = A^{-1} - A^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1}$$
$$(C^{-1} + DA^{-1}B)^{-1}DA^{-1} = CD(BCD + A)^{-1}$$
$$(C^{-1} + B^{t}A^{-1}B)^{-1}B^{t}A^{-1} = CB^{t}(BCB^{t} + A)^{-1}$$

#### Inverse of covariance matrix

Assume  $\Sigma$  positive definite (e.g. scaled identity matrix).

Then  $Z\Psi Z^T + \Sigma$  guaranteed to be positive definite and

$$(Z\Psi Z^{\mathsf{T}} + \Sigma)^{-1} = \Sigma^{-1} - \Sigma^{-1} Z (\Psi^{-1} + Z^{\mathsf{T}} \Sigma^{-1} Z)^{-1} Z^{\mathsf{T}} \Sigma^{-1}$$

Right hand side may be easier to evaluate if  $\Psi^{-1}$  and  $Z^T\Sigma^{-1}Z$  sparse (e.g. AR(1) random effects - next slide)

## Example AR(1) - covariance and inverse covariance

Consider  $U_1 = \nu_1$  and

$$U_i = aU_{i-1} + \nu_i, \quad i = 2, \ldots, m$$

where  $\nu_i$  independent zero-mean normal with variances  $\mathbb{V}\mathrm{ar}\nu_1=\tau_1^2$  and  $\mathbb{V}\mathrm{ar}\nu_i=\tau^2$ , i>1.

Then  $U = B\nu$  for some B so  $U \sim N_n(0, BCB^T)$  where  $C = \text{diag}(\tau_1^2, \tau^2, \dots, \tau^2)$ . Hence  $\Psi = BCB^T$  and  $\Psi^{-1} = (B^{-1})^T C^{-1} B^{-1}$ .

**NB**:  $B^{-1}$  and  $C^{-1}$  are sparse (many zeros) and hence allows fast computations. So is  $\Psi^{-1}$ !

Expressions for covariances simplify in the stationary case |a| < 1 and  $\tau_1^2 = \tau^2/(1-a^2)$ .

Limiting case  $a \to 1$  is improper pairwise difference density (Lec 1, Excs 9).

#### ANOVA models

ANOVA models arise when model specified using cross-combinations of factors/grouping variables or nested factors.

Example: one- and two-way analysis of variance.

Example: nested model for reflectance measurements.

E.g. one-way ANOVA: Z has entries  $Z_{(ij),q}=1$  i=q and 0 otherwise,  $i,q=1,\ldots,k$   $j=1,\ldots,m$ .

#### Likelihood for linear mixed model

log likelihood for linear mixed model with covariance matrix  $V(\psi) = Z\Psi Z^{\mathsf{T}} + \Sigma$ :

$$-\frac{1}{2}\log(|V(\psi)|) - \frac{1}{2}(y - X\beta)^{\mathsf{T}}V(\psi)^{-1}(y - X\beta)$$

 $\psi$ : parameters for covariance matrix (e.g. variance components)

## MLE and weighted least squares

Assume  $\psi$  known. MLE for  $\beta$  is weighted least squares estimate

$$\hat{\beta}(\psi) = \arg\min_{\beta} (y - X\beta)^{\mathsf{T}} V(\psi)^{-1} (y - X\beta)$$

Differentiate and equate to zero:

$$X^{\mathsf{T}}V(\psi)^{-1}(y-X\beta)=0 \Leftrightarrow \hat{\beta}(\psi)=(X^{\mathsf{T}}V(\psi)^{-1}X)^{-1}X^{\mathsf{T}}V(\psi)^{-1}y$$

(provided relevant inverses exist)

Covariance parameters  $\psi$ : often numerical optimization is needed to maximize profile likelihood

$$-\frac{1}{2}\log(|V(\psi)|) - \frac{1}{2}(y - X\hat{\beta}(\psi))^{\mathsf{T}}V(\psi)^{-1}(y - X\hat{\beta}(\psi))$$



## Estimation using orthogonal projections

Suppose  $Y \sim N_n(\mu, \sigma^2 I)$ ,  $\mu = X\beta$ . Let P be orthogonal projection on M = span(X) (assuming X full rank,  $P = X(X^TX)^{-1}X^T$ ).

Then by Pythagoras,  $\|Y - X\beta\|^2 = \|Y - PY\|^2 + \|PY - X\beta\|^2$ . Hence  $\hat{\mu} = Py$  and  $\hat{\beta} = (X^TX)^{-1}X^Ty$ .

Moreover 
$$\hat{\sigma}^2 = \|Y - PY\|^2 / n = \|Y - X\hat{\beta}\|^2 / n$$
.

Suppose now  $Y \sim N_n(\mu, \sigma^2 W)$  where  $W = LL^T$  fixed. Then MLE based on Y and  $\tilde{Y} = L^{-1}Y$  equivalent. Note  $\mathbb{C}\mathrm{ov}(\tilde{Y}) = \sigma^2 I$  and  $\mathbb{E}\tilde{Y} = L^{-1}X\beta = \tilde{X}\beta$ . Hence by the above,

$$\hat{\beta} = (\tilde{X}^{\mathsf{T}}\tilde{X})^{-1}\tilde{X}^{\mathsf{T}}\tilde{y} = (X^{\mathsf{T}}W^{-1}X)^{-1}X^{\mathsf{T}}W^{-1}y$$

and

$$\hat{\sigma}^2 = (y - X\hat{\beta})^{\mathsf{T}} W^{-1} (y - X\hat{\beta}) / n$$



### Profile likelihood - uncorrelated noise

Suppose 
$$\mathbb{C}\text{ov}\epsilon = \sigma^2 I$$
  $(n \times n)$  and  $\mathbb{C}\text{ov}U = \Psi = \tau^2 L(\theta) L(\theta)^T$   $(k \times k)$ 

Then  $(\psi = (\sigma^2, \theta, \phi))$ 

$$V(\psi) = \sigma^{2}(I + \phi Z L(\theta) L(\theta)^{\mathsf{T}} Z^{\mathsf{T}}) = \sigma^{2} W(\phi, \theta)$$

where  $\phi = \tau^2/\sigma^2$  (signal to noise ratio).

Given  $\phi$  and  $\theta$ ,

$$\hat{\beta}(\phi,\theta) = (X^{\mathsf{T}}W^{-1}(\phi,\theta)X)^{-1}X^{\mathsf{T}}W(\phi,\theta)^{-1}y$$

and

$$\hat{\sigma}^2(\phi,\theta) = \frac{1}{n} (y - X \hat{\beta}(\phi,\theta))^\mathsf{T} W(\phi,\theta)^{-1} (y - X \hat{\beta}(\phi,\theta))$$

Then use matrix identity and result on next slide to get

$$W(\phi, \theta)^{-1} = (I + \phi Z L(\theta) L(\theta)^{\mathsf{T}} Z^{\mathsf{T}})^{-1} = I - Z(\phi^{-1} (L(\theta)^{\mathsf{T}})^{-1} L(\theta)^{-1} + Z^{\mathsf{T}} Z)^{-1} Z^{\mathsf{T}}$$

and

$$|I_n + \phi Z L(\theta) L(\theta)^{\mathsf{T}} Z^{\mathsf{T}}| = |I_k + \phi L(\theta) L(\theta)^{\mathsf{T}} Z^{\mathsf{T}} Z|$$

Note: now we just need to invert/compute determinant of  $k \times k$  and typically k < n.

Profile log likelihood for  $(\phi, \theta)$ :

$$I(\phi, \theta) = -\frac{1}{2} \log |\hat{\sigma}^2(\phi, \theta)W(\phi, \theta)| - \frac{n}{2} \equiv -\frac{n}{2} \log \hat{\sigma}^2(\phi, \theta) - \frac{1}{2} \log |I_k + \phi L(\theta)L(\theta)^{\mathsf{T}} Z^{\mathsf{T}} Z|$$

#### Some further useful matrix results

Consider

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$$

Suppose  $A_{11}$  is invertible. Then

$$|A| = |A_{11}||A_{22} - A_{21}A_{11}^{-1}A_{12}|$$

Similarly, if  $A_{22}$  is invertible:  $|A| = |A_{22}||A_{11} - A_{12}A_{22}^{-1}A_{21}|$ 

Proof: use that

$$\begin{bmatrix} A_{11} & A_{12} \\ 0 & A_{22} - A_{21}A_{11}^{-1}A_{12} \end{bmatrix} = \begin{bmatrix} I & 0 \\ -A_{21}A_{11}^{-1} & I \end{bmatrix} A$$

Moreover, if  $A: n \times k$  and  $B: k \times n$  then

$$|I_n + AB| = |I_k + BA|$$

Proof: use above result on

$$\begin{bmatrix} I_n & -A \\ B & I_k \end{bmatrix}$$



#### MLE's of variances biased or inconsistent

For simple normal sample  $Y_i \sim N(\xi, \sigma^2)$ , MLE  $\hat{\sigma}^2$  is biased:

$$E\hat{\sigma}^2 = \sigma^2(n-1)/n$$

Bias arise from estimation of  $\xi$   $(\sum_i (y_i - \xi)^2 \text{ vs } \sum_i (y_i - \bar{y}_i)^2)$ .

Neyman-Scott example:  $y_{ij} = \xi_i + \epsilon_{ij}$ , i = 1, ..., k and j = 1, 2. MLE of  $\sigma^2$  not even consistent as k tends to infinity (exercise).

## REML (restricted/residual maximum likelihood)

Idea: linear transform of data which eliminates mean. Suppose design matrix  $X: n \times p$  and let  $A: n \times (n-p)$  have columns spanning the orthogonal complement  $M^{\perp}$  of  $M = \operatorname{span} X$ . Then  $A^{\mathsf{T}}X = 0$ .

Transformed data  $((n-p) \times 1)$ 

$$\tilde{Y} = A^{\mathsf{T}}Y = A^{\mathsf{T}}ZU + A^{\mathsf{T}}\epsilon$$

has mean 0 and covariance matrix  $A^{\mathsf{T}}V(\psi)A$ . Then proceed as for MLE.

NB: suppose A and B both span  $M^{\perp}$ . Then the same REML estimate of  $\psi$  is obtained (proof: B = AC for an invertible matrix C, write out likelihoods for  $\tilde{Y}$  using A and AC).

NB:  $M^{\perp}$  is the null-space of  $X^{\mathsf{T}}$ .

#### REML continued

Given REML estimate  $\hat{\psi}$  we use weighted least squares estimate of  $\beta$  :

$$\hat{\beta} = (X^{\mathsf{T}} V(\hat{\psi})^{-1} X)^{-1} X^{\mathsf{T}} V^{-1} (\hat{\psi}) y$$

## REML examples

Simple normal sample: A has columns  $e_i - 1_n/n$ , i = 1, ..., n-1 where  $1_n$  is the *n*-vector of 1's and  $e_i$  is the *i*th standard basis vector.

Alternative: use columns  $e_i - e_n$ , i = 1, ..., n - 1.

Neyman-Scott problem:  $A^T$  has rows of the form  $(1,-1,0,\ldots,0)$ ,  $(0,0,1,-1,0,\ldots,0)$  etc.

### Implementation of REML - uncorrelated noise

Suppose 
$$\mathbb{C}\text{ov}\epsilon = \sigma^2 I$$
 and  $\mathbb{C}\text{ov}U = \Psi = \tau^2 L(\theta) L(\theta)^\mathsf{T}$ 

Then

 $\hat{\sigma}^2(\phi,\theta) =$ 

$$V(\psi) = \sigma^2 (I + \phi Z L(\theta) L(\theta)^{\mathsf{T}} Z^{\mathsf{T}}) = \sigma^2 W(\phi, \theta)$$
 where  $\phi = \tau^2 / \sigma^2$ .

Choose A so that columns form an orthogonal basis for  $M^{\perp}$  where  $M = \operatorname{span} X$ . Then  $A^{\mathsf{T}} A = I$  and  $AA^{\mathsf{T}} = I - X(X^{\mathsf{T}} X)^{-1} X^{\mathsf{T}}$  (since  $AA^{\mathsf{T}}$  is a projection matrix).

$$\mathbb{C}\mathrm{ov}A^\mathsf{T}Y = A^\mathsf{T}V(\psi)A = \sigma^2(I + \phi A^\mathsf{T}ZL(\theta)L(\theta)^\mathsf{T}Z^\mathsf{T}A) \quad (n-p)\times (n-p)$$
 Hence given  $(\phi,\theta)$  estimate of  $\sigma^2$  is (using Woodbury)

$$\frac{1}{n-p} \left[ \tilde{Y}^{\mathsf{T}} \tilde{Y} - \tilde{Y}^{\mathsf{T}} A^{\mathsf{T}} Z [\phi^{-1} (L(\theta) L(\theta)^{\mathsf{T}})^{-1} + Z^{\mathsf{T}} A A^{\mathsf{T}} Z]^{-1} Z^{\mathsf{T}} A \tilde{Y} \right]$$

Profile REML log likelihood for  $(\phi, \theta)$ :

$$I(\phi, \theta) = -\frac{n-p}{2} \log \hat{\sigma}^2(\phi, \theta) - \frac{1}{2} \log |I + \phi Z^{\mathsf{T}} A A^{\mathsf{T}} Z L(\theta) L(\theta)^{\mathsf{T}}|$$

Note: depends only on A through  $AA^{\mathsf{T}} = I - X(X^{\mathsf{T}}X)^{-1}X^{\mathsf{T}}$ . This again shows that specific choice of basis for  $M^{\perp}$  does not matter.

(if columns in A not orthogonal, we would have  $A(A^TA)^{-1}A^T = I - X(X^TX)^{-1}X^T$  and reach the same conclusion)

## MLE for balanced one-way ANOVA

Maximizing likelihood for balanced one-way (M&T Thm 5.4 and remarks 5.13-5.16)

$$\hat{\xi} = \bar{y}_{\cdot\cdot\cdot}, \hat{\sigma}^2 = \frac{SSE}{k(m-1)}, \hat{\tau}^2 = \frac{SSB/k - \hat{\sigma}^2}{m}$$

$$\mathbb{E}\hat{\sigma}^2 = \sigma^2 \quad \mathbb{E}SSB/k = \frac{k-1}{k}\sigma^2 + m\frac{k-1}{k}\tau^2$$

Hence  $\hat{\tau}^2$  biased. It is asymptotically unbiased as k tends to infinity.

In lecture 3 we derive the MLEs using orthogonal projections.

## REML for balanced one-way ANOVA

E.g. A as for simple normal sample, i.e.  $\tilde{y}_{ij} = y_{ij} - \bar{y}_{..}$ 

Then REML equations for estimating  $\tau^2$  and  $\sigma^2$  coincide with the moment equations from lecture 1.

#### Maximization

**NB:** In general profile likelihoods (MLE or REML) must be maximized numerically (e.g. Newton-Raphson).

For one-way ANOVA we can do it by hand in closed form but tedious.

In special case of balanced ANOVA models orthogonal decomposition makes MLE very easy (later)

## Computational details

For the general linear mixed model computational complexity arises from the need to invert and compute determinant of  $V(\psi)$ .

Strategies covered here include using possible sparsity of  $\Psi$  or possible low dimension k << n of  $\Psi$ 

Usually we just need to specify X and Z and then general software (R or SAS) takes care of numerical details and maximization.

#### Exercises

- Slides 4-5 contain 3 specifications of the distribution of Y.
   Show that these are equivalent (hint: calculate characteristic function (lecture 1) in case of the hierarchical specification)
- 2. formulate random intercept and slope model

$$y_{ij} = \beta_0 + \beta_1 x_{ij} + U_i + V_i x_{ij} + \epsilon_{ij}$$

as general linear mixed model. What are the design matrices  $\boldsymbol{X}$  and  $\boldsymbol{Z}$  ?

- 3. (AR(1)-model) Consider the 'stationary' case |a| < 1 and  $\tau_1^2 = \tau^2/(1-a^2)$ .
  - 3.1 Show  $U_i \sim N(0, \tau^2/(1-a^2)) \Rightarrow U_{i+1} \sim N(0, \tau^2/(1-a^2))$ .
  - 3.2 Identify  $B^{-1}$  and B and compute  $\Psi$  and  $\Psi^{-1}$ .
  - 3.3 Formulate  $V^{-1} = (\Psi + \sigma^2 I)^{-1}$  in terms of sparse matrices where V is covariance matrix for the model  $Y_i = \xi + U_i + \epsilon_i$  (AR(1)+noise).
  - 3.4 Consider the limit as  $a \to 1$  of the density of an AR(1) with  $\tau_1^2 = \tau^2/(1-a^2)$ . How is this related to the smoothing prior in Exercise 9 from lecture 1?

- 4. Show that the REML variance estimate for a simple normal sample coincides with  $s^2 = \sum_{i=1}^n (y_i \bar{y}_i)^2/(n-1)$ .
- 5. Compute MLE and REML estimates for the Neyman-Scott example. Compute mean and variance for the estimates of  $\sigma^2$ .
- Show that if A and B both span the orthogonal complement of spanX then the same REML estimates are obtained from A<sup>T</sup>Y and B<sup>T</sup>Y.
- Go carefully through the derivations leading to REML profile log likelihood (slide 20-21).
- 8. Suppose Y has a parametric density  $f_Y(\cdot;\theta)$  and  $\tilde{Y}=T(Y)$  for a differentiable and invertible transformation T that does not depend on  $\theta$ . Show that the MLE for  $\theta$  based on Y coincides with the MLE of  $\theta$  based on  $\tilde{Y}$ .

Further, assume  $\psi = g(\theta)$  for some invertible transformation g. Show that the MLE of  $\theta$  coincides with  $g^{-1}(\hat{\psi})$  where  $\hat{\psi}$  is the MLE of  $\psi$  ( $\hat{\psi} = \operatorname{argmax}_{\psi} f(y; g^{-1}(\psi))$ ).

9. In case of simple normal sample compute variance of MLE  $\hat{\sigma}^2$  and REML estimate  $s^2$  given that  $\sum_{i=1}^n (Y_i - \bar{Y})^2$  is  $\sigma^2 \chi^2 (n-1)$  (hint:  $\mathbb{V}ar\chi^2 (f) = 2f$ ).

Which estimator has smallest mean square error? (recall mean square error is sum of variance and squared bias)