### Markov random fields I

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- 1. specification of joint distributions
- 2. conditional specifications
- 3. conditional auto-regression
- 4. Brooks factorization
- 5. conditional independence and graphs
- 6. Hammersley-Clifford

# Specification of joint distributions

Consider random vector  $(X_1, \ldots, X_n)$ .

How do we specify its joint distribution ?

- 1. assume  $X_1, \ldots, X_n$  independent but often not realistic
- 2. assume  $(X_1, \ldots, X_n)$  jointly normal and specify mean vector and covariance matrix (i.e. positive definite  $n \times n$  matrix)
- 3. use copula (e.g. transform marginal distributions of joint normal)
- 4. specify  $f(x_1)$ ,  $f(x_2|x_1)$ ,  $f(x_3|x_1, x_2)$  etc.
- specify full conditional distributions X<sub>i</sub>|X<sub>-i</sub> but what is then joint distribution and does it exist ?
   (X<sub>-i</sub> = (X<sub>1</sub>,..., X<sub>i-1</sub>, X<sub>i+1</sub>,..., X<sub>n</sub>))

In this part of the course we will consider the fifth option.

### Conditional auto-regressions

Suppose  $X_i | X_{-i}$  is normal.

Auto-regression natural candidate for conditional distribution:

$$X_i|X_{-i} = x_{-i} \sim N(\alpha_i + \sum_{l \neq i} \gamma_{il} x_l, \kappa_i)$$
(1)

Equivalent (under certain conditions, see exercise) and more convenient:

$$X_i|X_{-i} = x_{-i} \sim \mathcal{N}(\mu_i - \sum_{l \neq i} \beta_{il}(x_l - \mu_l), \kappa_i)$$
(2)

Is this consistent with a multivariate normal distribution  $N_n(\mu, \Sigma)$  for X ?

## Brook's lemma

Consider two outcomes x and y of X where X has joint density p where p(y) > 0.

Brooks factorization:

$$\frac{p(x)}{p(y)} = \prod_{i=1}^{n} \frac{p_i(x_i|x_1, \dots, x_{i-1}, y_{i+1}, \dots, y_n)}{p_i(y_i|x_1, \dots, x_{i-1}, y_{i+1}, \dots, y_n)}$$

Note n! ways to factorize !

If conditional densities consistent with joint density, we can choose fixed y and determine p(x) by

 $p(x) \propto p(x)/p(y)$ 

where RHS evaluated using Brook's factorization.

Application to conditional normal specification

We let 
$$y=\mu=(\mu_1,\ldots,\mu_n).$$
 Then

$$\log\left(\frac{p_{i}(x_{i}|x_{1},...,x_{i-1},\mu_{i+1},...,\mu_{n})}{p_{i}(\mu_{i}|x_{1},...,x_{i-1},\mu_{i+1},...,\mu_{n})}\right)$$
  
=  $-\frac{1}{2\kappa_{i}}[(x_{i}-\mu_{i}+\sum_{l=1}^{i-1}\beta_{il}(x_{l}-\mu_{l}))^{2}-(\sum_{l=1}^{i-1}\beta_{il}(x_{l}-\mu_{l})^{2}]$   
=  $-\frac{1}{2\kappa_{i}}[(x_{i}-\mu_{i})^{2}+2\sum_{l=1}^{i-1}\beta_{il}(x_{i}-\mu_{i})(x_{l}-\mu_{l})]$ 

Assume now  $\beta_{ij}/\kappa_i=\beta_{ji}/\kappa_j.$  Then (you do the algebra)

$$\log p(x) = \log p(\mu) - \frac{1}{2} \sum_{i=1}^{n} \sum_{l=1}^{n} \frac{\beta_{il}}{\kappa_i} (x_i - \mu_i) (x_l - \mu_l)$$
(3)

with  $\beta_{ii} = 1$ .

Easy to see that this is consistent with (2)

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This is formally equivalent to a multivariate Gaussian density with mean vector  $\mu$  and precision matrix  $Q = \Sigma^{-1} = [q_{ij}]_{ij}$  with  $q_{ij} = \beta_{ij}/\kappa_i$ .

A well-defined Gaussian density provided Q is symmetric and positive definite (whereby  $\Sigma = Q^{-1}$  positive definite and symmetric)

We already assumed symmetry

$$q_{ij} = q_{ji} \Leftrightarrow \beta_{ij}/\kappa_i = \beta_{ji}/\kappa_j \Leftrightarrow \beta_{ij}\kappa_j = \beta_{ji}\kappa_i$$

Positive definiteness must be checked by considering the whole of Q.

There are *n*! factorizations. In general

$$\frac{p(x)}{p(y)} = \prod_{i=1}^{n} \frac{p_{\pi(i)}(x_{\pi(i)}|x_{\pi(1)}, \dots, x_{\pi(i-1)}, y_{\pi(i+1)}, \dots, y_{\pi(n)})}{p_{\pi(i)}(y_{\pi(i)}|x_{\pi(1)}, \dots, x_{\pi(i-1)}, y_{\pi(i+1)}, \dots, y_{\pi(n)})}$$

where  $(\pi(1), \ldots, \pi(n))$  represents a permutation of  $(1, 2, \ldots, n)$ .

In case of (2) we obtain in the same manner as before

$$\log p(x) = \log p(\mu) - \frac{1}{2} \sum_{i=1}^{n} \sum_{l=1}^{n} \frac{\beta_{\pi(i)\pi(l)}}{\kappa_{\pi(i)}} (x_{\pi(i)} - \mu_{\pi(i)}) (x_{\pi(l)} - \mu_{\pi(l)})$$

which in fact coincides with (3) (just a reordering of the double sum) - hence choice of  $\pi$  does not matter.

Conditional distribution of  $X_i$  for  $N(\mu, Q^{-1})$ 

$$p_i(x_i|x_{-i}) \propto \exp(-rac{1}{2}(x_i - \mu_i)^2 Q_{ii} - \sum_{k \neq i} (x_i - \mu_i)(x_k - \mu_k) Q_{ik})$$

For a normal distribution  $Y \sim N(\xi, \sigma^2)$ ,

$$p(y) \propto \exp(-rac{1}{2\sigma^2}y^2 + rac{1}{\sigma^2}y\xi)$$

Comparing the two above equations we get (again you do the algebra)

$$X_i | X_{-i} = x_{-i} \sim N(\mu_i - \frac{1}{Q_{ii}} \sum_{k \neq i} Q_{ik}(x_k - \mu_k), Q_{ii}^{-1})$$

Thus auto-regressions on slide 4 are in fact general forms of the conditional distributions for a multivariate normal distribution !

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# Example: Gaussian random field on 1D lattice

Consider lattice  $V = \{l | l = 1, ..., L\}$ . Define  $\mu_i = 0$ ,  $\kappa_i = \beta_{ii} = 1$ and for some  $\beta \neq 0$  define

$$eta_{ij} = egin{cases} eta & |i-j| \mod (L-2) = 1 \ 0 & ext{otherwise} \end{cases}$$

 ${\it Q}$  obviously symmetric.  ${\it Q}$  not positive definite if  $\beta=-1/2.$ 

Q positive definite  $\Leftrightarrow |\beta| < 1/2$ 

Note this is an example of a *circulant* precision matrix/random field: if we say i, j are neighbours if  $\beta_{ij} \neq 0$  then we obtain circular graph on V.

(exercise in case L = 4 - consider determinant of Q)

Case L = 4

-3 graph.

Q in case L-4 [ p 0 p p 1 p 0 0 p 1 p p 0 p 1 p 0 p

### Example: Gaussian random field on 2D lattice

Consider lattice  $V = \{(I, k) | I = 1, ..., L, k = 1, ..., K\}$ . Now indices  $i, j \in V$  correspond to points  $(i_1, i_2)$  and  $(j_1, j_2)$  Define  $i, j \in V$  to be neighbours  $i \sim j \Leftrightarrow |i_1 - j_1| + |i_2 - j_2| = 1$  (*i* and *j* horizontal or vertical neighbours).

Tempting: define  $\mu_i = 0$ ,

$$eta_{ij} = egin{cases} -1/\# N_i & i \sim j \ 0 & ext{otherwise} \end{cases}$$

where  $\#N_i$  is number of neighbours (2, 3, or 4) of *i* and  $\kappa_i = \kappa/\#N_i > 0$  where  $\kappa > 0$ . Recall also  $\beta_{ii} = 1$ 

Then

$$X_i|X_{-i} = x_{-i} \sim N(rac{1}{\#N_i}\sum_{j\sim i}x_j,\kappa/\#N_i)$$

has conditional mean given by average of neighbours and conditional variance inversely proportional to number of neighbours.

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Case K = L = 3

L = K = 3 I = I

Case K = L = 3 continued

Problem: resulting Q is positive semi definite:  $x^{\mathsf{T}}Qx = 0 \Leftrightarrow x = a\mathbf{1}_n$  for some  $a \in \mathbb{R}$ .

Why: *i*th row of  $\kappa^{-1}Q$  has *i*th entry  $\#N_i$  and  $N_i$  entries equal to -1. Rest zero. Consider e.g. specific case L = K = 3 to see what happens.

We can modify by  $Q := Q + \frac{\tau}{\kappa}I$  where  $\tau > 0$ . Then modified Q is positive definite and we obtain modified conditional distributions

$$X_i|X_{-i} = x_{-i} \sim N(\mu_i + rac{1}{\#N_i + au}\sum_{k
eq i}(x_k - \mu_k), rac{\kappa}{\#N_i + au})$$

which are consistent with joint multivariate distribution.

For the record: we can make sense of multivariate distributions with positive-semidefinite  $\Sigma$  as distributions on lower dimensional subspaces. Then Q is generalized inverse of  $\Sigma$ .

# Conditional vs. marginal modeling

Usually we model multivariate normal in terms of  $\boldsymbol{\Sigma}$  - i.e. covariance structure well understood.

Modeling in terms of conditional distributions (or equivalently Q) appealing but downside is that we do not necessarily know structure of  $\Sigma$  - although it can be computed numerically by inverting Q.

You are invited to invert Q from previous example L = K = 3 with  $\tau > 0$ .

### Markov random fields

Let V denote a finite set of vertices and E a set of edges where an element e in E is of the form  $\{i, j\}$  for  $i \neq j \in V$ . (i.e. an edge is a unordered pair of vertices). G = (V, E) is a graph.

 $i, j \in V$  are neighbours,  $i \sim j$ , if  $\{i, j\} \in E$ .

A random vector  $X = (X_i)_{i \in V}$  is a Markov random field with respect to G if

$$p_i(x_i|x_{-i}) = p_i(x_i|x_{N_i})$$

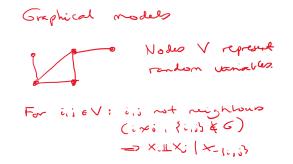
where  $N_i$  is the set of neighbours of i and for  $x = (x_i)_{i \in V}$  and  $A \subseteq V$ ,  $x_A = (x_i)_{i \in A}$ .

In other words,  $X_i$  and  $X_j$  are conditionally independent given  $X_{-\{i,j\}}$  if *i* and *j* are not neighbours.

Markov random field is another word for graphical model.

# Graphical model

Model where conditional dependence structure specified by graph.



### Hammersley-Clifford theorem

Consider a positive density  $p(\cdot) > 0$  for  $X = (X_i)_{i \in V}$  and a graph G = (V, E). Then the following statements are equivalent: 1. X is a MRF wrt G. 2.

$$p(x) = \prod_{C \subseteq V} \phi_C(x_C)$$

for interaction functions  $\phi_C$  where  $\phi_C = 1$  unless *C* is a clique wrt. *G*. We can further introduce the constraint  $\phi_C(x_C) = 1$  if  $x_l = y_l$  for  $l \in C$  and some fixed *y*. Then the interaction functions are uniquely determined.

Notation: for ease of notation we often write *i* for  $\{i\}$  and  $(x_A, y_B)$  will denote a vector with entries  $x_i$  for  $i \in A$  and  $y_j$  for  $j \in B$ ,  $A \cap B = \emptyset$  (this is a convenient but not rigorous notation)

Clique:  $C \subseteq V$  is a clique if  $i \sim j$  for all  $i \neq j \in C$ (in particular, all singletons  $C = \{i\}$  are cliques) Proof: 2.  $\Rightarrow$  1.

$$p_i(x_i|x_{-i}) \propto \prod_{C \subseteq V: C \cap i \neq \emptyset} \phi_C(x_C)$$

RHS depends only on  $x_j \in N_i$ : if  $l \in C$  is not a neighbour of *i* then *C* can not be a clique. Then  $\phi_C(x_C) = 1$  so it does not depend on  $x_l$ .

 $1. \Rightarrow 2.$ 

We choose an arbitrary reference outcome y for X. We then define  $\phi_{\emptyset} = p(y)$  and, recursively,

 $\phi_C(x_C) = \begin{cases} 1 & C \text{ not a clique or } x_l = y_l \text{ for some } l \in C \\ \frac{p(x_C, y_{-C})}{\prod_{B \subset C} \phi_B(x_B)} & \text{otherwise} \end{cases}$ 

Let  $x = (x_A, y_{-A})$  where  $x_I \neq y_I$  for all  $I \in A$ . We show 2. by induction in the cardinality |A| of A. If |A| = 0 then x = y and  $p(y) = \phi_{\emptyset}$  so 2. holds. Assume now that 2. holds for |A| = k - 1 where  $k \leq |V|$  and consider A with |A| = k.

Assume A is a clique. Then by construction,

$$p(x_A, y_{-A}) = \phi_A(x_A) \prod_{B \subset A} \phi_B(x_B)$$

and we are done since for  $C \subseteq V$  which is not a subset of A we have  $\phi_C((x_A, y_{-A})_C) = 1$  by construction

NB: don't need induction hypothesis in this case,

Assume A is not a clique, i.e. there exist  $l, j \in A$  so that  $l \not\sim j$ . Then

$$p(x_A, y_{-A}) = \frac{p_l(x_l|x_{A\setminus l}, y_{-A})}{p_l(y_l|x_{A\setminus l}, y_{-A})} p(x_{A\setminus l}, y_{-A}, y_l)$$

$$= \frac{p_l(x_l|x_{A\setminus \{l,j\}}, y_j, y_{-A})}{p(y_l|x_{A\setminus \{l,j\}}, y_j, y_{-A})} p(x_{A\setminus l}, y_{-A}, y_l)$$

$$= \frac{p_l(x_l, x_{A\setminus \{l,j\}}, y_j, y_{-A})}{p_l(y_l, x_{A\setminus \{l,j\}}, y_j, y_{-A})} p(x_{A\setminus l}, y_{-A}, y_l)$$

$$= \frac{\prod_{C \subseteq A\setminus \{l,j\}} \phi_C(x_C)}{\prod_{C \subseteq A\setminus \{l,j\}} \phi_C(x_C)} \prod_{C \subseteq A\setminus l} \phi_C(x_C)$$

$$= \prod_{C \subseteq A} \phi_C(x_C)$$

where second "=" by 1. and fourth "=" by induction. Thus 2. also holds in this case.

NB: At the expense of further tecnicalities HC-theorem can be generalized to the case of a not strictly positive  $p(\cdot)$ .

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### Exercises

1. Show that two parametrizations (1) and (2) are equivalent under the condition that the matrix A with  $A_{ii} = 1$  and  $A_{ij} = -\gamma_{ij}$  is invertible. In other words, show that there is an invertible mapping between the parameter vectors  $(\alpha_1, \ldots, \alpha_n, \gamma_{12}, \ldots, \gamma_{(n-1)n})$  and  $(\mu_1, \ldots, \mu_n, \beta_{12}, \ldots, \beta_{(n-1)n})$ .

Hint: equate the conditional means for all i = 1, ..., n.

- 2. Verify Brook's Lemma.
- 3. Perform derivations left to the reader at slides 6 and 9
- 4. Show that a precision matrix, if it exists, is positive definite.
- 5. Check in case L = 4 for circulant Gaussian that Q is positive definite if and only if  $|\beta| < 1/2$  (one criterion for this is that all leading principal submatrices have positive determinants)
- 6. Compute numerically the inverse of Q for circulant Gaussian (L = 4, β = -0.3, 0.3) and inverse of Q + τI for various τ = 0.01, 0.1, 1 in case of 2D Gaussian with L = K = 3 (slides 10 and 12). Also consider the correlation matrix: (E) (E) = E

## Conditional independence

Suppose X, Y, Z are random variables (or vectors). Then we define X and Y to be conditionally independent given Z if

$$p(x, y|z) = p(x|z)p(y|z)$$

The following statements are equivalent:

 $(p(\cdot)$  generic notation for (possibly conditional) probability densities)