

# Outline

## 1 Basic concepts

- Density function
- The mean
- Variance and Standard deviation
- Distribution function

## 2 The normal distribution

- The standard normal
- The general normal distribution

## 3 Joint and conditional distribution

- Pairwise independence
- Mutual independence and sample

## 4 Sample from a normal distribution

- Estimating the mean in the normal distribution
- Estimating the variance in the normal distribution with known mean
- Distribution of variance estimate when mean is known
- The chi-square distribution
- Estimating the variance in the normal distribution with unknown

# Defining the density function

Let  $X$  be a continuous random variable.

Then it holds for its *density function*  $f_X(x)$  that

$$f_X(x) \geq 0$$

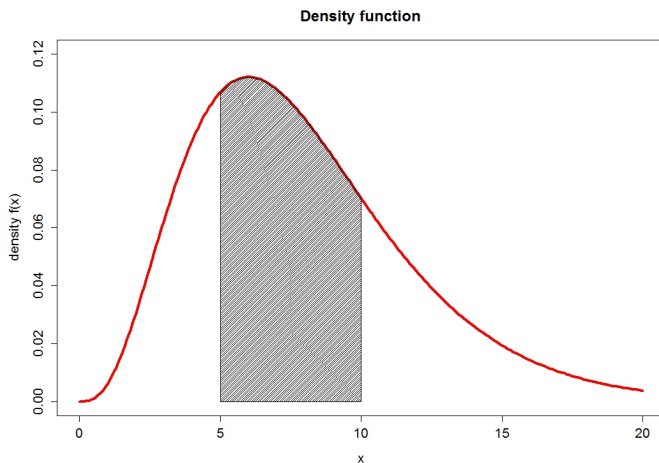
and for an interval  $[a, b]$  that

$$P(X \in [a, b]) = \int_a^b f_X(x) dx.$$

In particular

$$P(X \in \mathbb{R}) = \int_{-\infty}^{\infty} f_X(x) dx = 1.$$

# Example of a density



$P(X \in [5, 10])$  is the area of the shaded region.

# Mean of $X$

The *mean* of  $X$  is defined as

$$E(X) = \int_{-\infty}^{\infty} x f_X(x) dx.$$

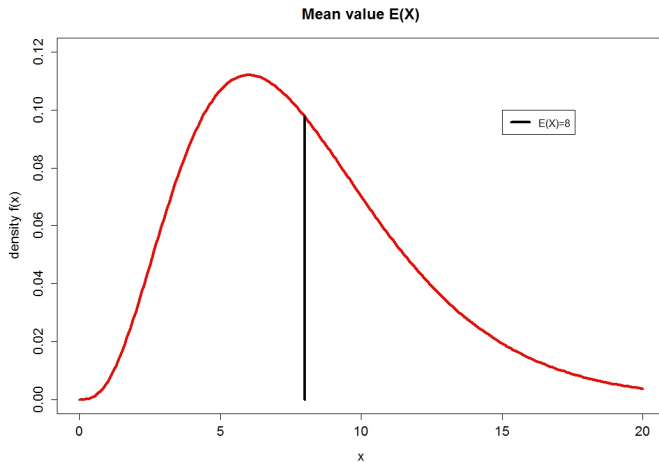
If  $h$  is a real function and  $Y = h(X)$ , then it holds that

$$E(Y) = E\{h(X)\} = \int_{-\infty}^{\infty} h(x)f_X(x) dx.$$

Especially, for real numbers  $a$  and  $b$

$$E(aX + b) = aE(X) + b.$$

# Mean is center of gravity



## Variance of $X$

The error on  $X$  is the deviation from the mean:  $\varepsilon = X - E(X)$ . On average the error is zero:  $E(\varepsilon) = 0$ .

The *variance* of  $X$  is defined as the average *squared* error:

$$\text{Var}(X) = E \left[ \{X - E(X)\}^2 \right] = E(\varepsilon^2).$$

If  $a$  and  $b$  are real numbers, then it holds that the squared error is changed by the square of the unit change

$$\text{Var}(aX + b) = a^2 \text{Var}(X).$$

The *standard deviation/spread* of  $X$  is defined as

$$\text{Spr}(X) = \sqrt{\text{Var}(X)},$$

and it holds that

$$\text{Spr}(aX + b) = |a| \text{Spr}(X).$$

# Distribution function

The *distribution function* of  $X$  is defined as

$$F_X(x) = P(X \leq x) = P(X \in ] - \infty, x]) = \int_{-\infty}^x f_X(t) dt,$$

which implies that

$$f_X(x) = \frac{d}{dx} F_X(x) = F'_X(x).$$

Furthermore it holds that

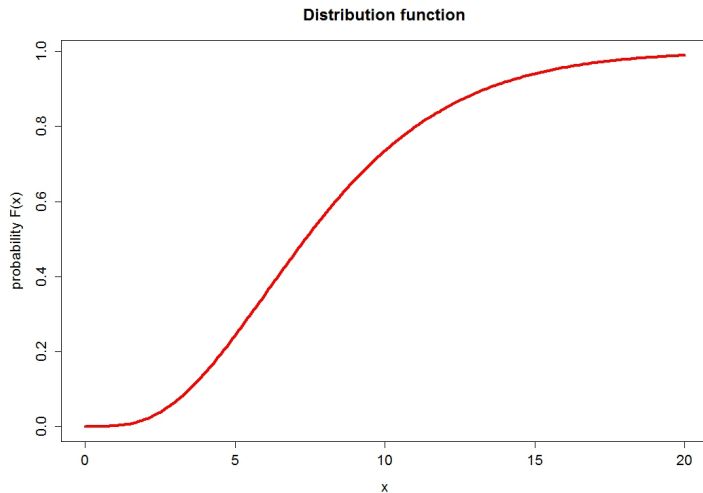
$$P(X \in [a, b]) = F_X(b) - F_X(a)$$

The  $\alpha$ -quantile,  $x_\alpha$ , for  $X$  is given by

$$F_X(x_\alpha) = \alpha.$$



# Example of a distribution function



## More on distribution function

Let  $Y = aX + b$ , for  $a > 0$  and  $b$  a real number.

Then it holds that

$$F_Y(y) = P(aX + b \leq y) = P\left(X \leq \frac{y-b}{a}\right) = F_X\left(\frac{y-b}{a}\right),$$

i.e.

$$F_{aX+b}(y) = F_X\left(\frac{y-b}{a}\right),$$

and further by differentiation

$$f_{aX+b}(y) = \frac{1}{a} f_X\left(\frac{y-b}{a}\right).$$

# The standard normal distribution

If  $Z$  is *standard normal distributed* it has density function  $f_Z = \phi$ , where

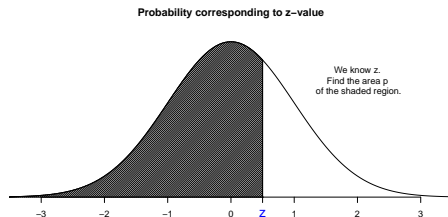
$$\phi(z) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{z^2}{2}\right), -\infty < u < \infty.$$

It holds that  $E(Z) = 0$  and  $\text{Var}(Z) = 1$ . It is also called the *Z-distribution*. The distribution function  $F_Z = \Phi$  is given by

$$\Phi(a) = \int_{-\infty}^a \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{z^2}{2}\right) dz.$$

The integral can not be solved explicitly, so: tables or software.

# Probabilities of the standard normal



Density of standard normal distribution

May be determined using python.

```
>>> norm.cdf([.5,1,2,3])  
array([ 0.69146246,  0.84134475,  0.97724987,  0.9986501 ])
```

# The general normal distribution

Let  $\sigma > 0$ ,  $\mu$  be real numbers, and let  $Y = \sigma Z + \mu$ . Then the density function for  $Y$  is

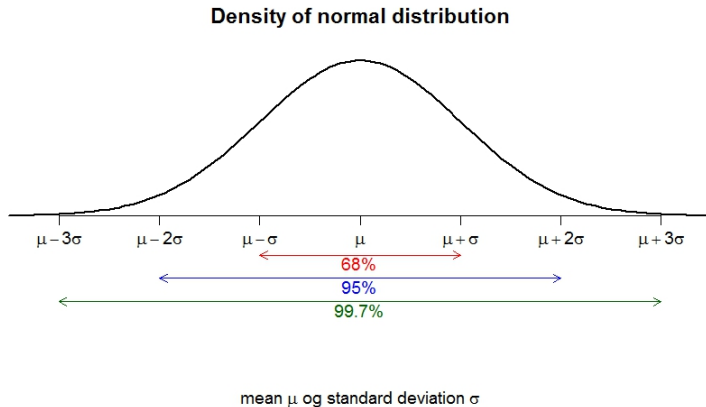
$$f_Y(y) = \frac{1}{\sigma} \Phi\left(\frac{y - \mu}{\sigma}\right) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(y - \mu)^2}{2\sigma^2}\right\}.$$

The distribution of  $Y$  is called a *normal distribution with mean  $\mu$  and variance  $\sigma^2$* . Often you write:  $Y \sim \mathcal{N}(\mu, \sigma^2)$ . The distribution function of  $Y$  is

$$F_Y(y) = \Phi\left(\frac{y - \mu}{\sigma}\right).$$

Hereby it is possible to find probabilities in a general normal distribution with mean  $\mu$  and variance  $\sigma^2$  by  $\Phi$  - standardize:  $Y \sim \mathcal{N}(\mu, \sigma^2)$ , then  $Z = \frac{Y - \mu}{\sigma} \sim \mathcal{N}(0, 1)$ .

# Normal density function



# Conditional distribution

Let  $X, Y$  be stochastic variables.

- The joint distribution of  $X$  and  $Y$  is specified by the probabilities of all interval pairs  $(I, J)$ :  $P(X \in I \text{ and } Y \in J)$ .

Suppose  $P(Y \in J) > 0$ . We shall limit the experiment to the case where we have observed  $Y \in J$ . In that case we define the conditional distribution of  $X$  given  $Y \in J$

$$P(X \in I | Y \in J) = \frac{P(X \in I \text{ and } Y \in J)}{P(Y \in J)}$$

# Pairwise independence

$X$  is said to be independent of  $Y$  if for all interval pairs  $(I, J)$ :

$$P(X \in I | Y \in J) = P(X \in I)$$

i.e. the distribution of  $X$  is not influenced by knowledge about  $Y$ .

We may rewrite the relation as

$$P(X \in I, Y \in J) = P(X \in I \text{ and } Y \in J) = P(X \in I)P(Y \in J)$$

i.e. the relation is symmetric and we simply say that  $X$  and  $Y$  are independent if this product relation is true for all interval pairs.



# A sample

A set  $X_1, \dots, X_n$  of random variables are independent if

$$P(X_1 \in I_1, \dots, X_n \in I_n) = \prod_{i=1}^n P(X_i \in I_i)$$

for any set  $I_1, \dots, I_n$  of intervals.

$X_1, \dots, X_n$  is said to be a **sample** if they are independent and

$$P(X_1 \in I) = \dots = P(X_n \in I)$$

i.e. they have the same distribution.

## Estimating the mean in the normal distribution

Suppose  $X_1, \dots, X_n$  is a sample from  $\mathcal{N}(\mu, \sigma^2)$ , where  $\mu$  is assumed unknown.

From the sample we want to derive an **estimate**(qualified guess) of  $\mu$ . We shall use the estimate

$$\hat{\mu} = \bar{x} = \frac{x_1 + \dots + x_n}{n} = \frac{1}{n} \sum_{i=1}^n x_i$$

The corresponding random variables  $\bar{X}$  has

- a normal distribution with mean value  $\mu$
- variance  $\frac{\sigma^2}{n}$

Properties of the estimator:

- $\bar{X}$  is **unbiased**, which means that  $E(\bar{X}) = \mu$ , i.e. on average we get the true value.
- $\bar{X}$  is **efficient**, which means that any other unbiased estimator, has a higher variance than  $\bar{X}$ .

## Example

We have measured the difference in height between A and B 3 times (in mm) and have observed:  $x_1 = 119, x_2 = 112, x_3 = 114$ .

Parameter:

- $\mu$  - the true difference in height

Estimate of  $\mu$ :

①  $\hat{\mu} = \bar{x} = (x_1 + x_2 + x_3)/3 = 115$

An alternative estimator is the so-called **median**  $x_M = x_{(2)} = 114$  where  $x_{(1)} = 112 < x_{(2)} = 114 < x_{(3)} = 119$  are the ordered measurements. It is unbiased but inefficient.

On the other hand it is **robust**. A clerical error like  $x_1 = 191, x_2 = 112, x_3 = 114$  yields the same median, whereas the mean is heavily influenced by the error as  $\bar{x} = 139$ .

# Estimating the variance in the normal distribution with known mean

Suppose  $X_1, \dots, X_n$  is a sample from  $\mathcal{N}(\mu_0, \sigma^2)$ , where  $\mu_0$  is assumed known, whereas  $\sigma$  is unknown.

From the sample we want to derive an estimate of  $\sigma$ .

- The error on the  $i$ 'th measurement is  $e_i = x_i - \mu_0$

As  $\sigma^2$  is the average squared error we use the estimate

$$s_0^2 = \frac{1}{n} \sum_{i=1}^n e_i^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu_0)^2$$

It can be shown that the estimator  $S_0^2$  is both unbiased and efficient.

## Example

We have measured the difference in height between A and B 3 times (in mm) and have observed:  $x_1 = 119$ ,  $x_2 = 112$ ,  $x_3 = 114$ .

Assume that the true height is  $\mu_0 = 113$ . Sum of squared errors

$$sse = (119 - 113)^2 + (112 - 113)^2 + (114 - 113)^2 = 38$$

Unbiased estimate of  $\sigma^2$

- $s_0^2 = \frac{38}{3} = 12.67 \text{ mm}^2$

Corresponding estimate of the standard deviation

- $s_0 = \sqrt{\frac{38}{3}} = 3.56 \text{ mm}$

# Distribution of variance estimate when mean is known

Define

- $Z_i = \frac{X_i - \mu_0}{\sigma} \quad i = 1, \dots, n$

Then these standardized errors are  $\mathcal{N}(0, 1)$

The estimator of the variance obeys

- $\frac{nS_0^2}{\sigma^2} = \sum_{i=1}^n Z_i^2$

The distribution of a sum of squares of a sample from the standard normal distribution is called the **chi-square distribution** - in greek the  $\chi^2$ -distribution.

# $\chi^2$ -distribution

Let  $Z_1, \dots, Z_d$  be independent standard normal distributed, then

$$Y = Z_1^2 + \dots + Z_d^2$$

is said to be  $\chi^2$ -*distributed* with  $d$  degrees of freedom.

The sum of squares of error by least squares adjustment with  $d$  redundants, is in fact a scaled  $\chi^2$ -distribution with  $d$  degrees of freedom. This has been shown by the german geodetic researcher F. R. Helmert in 1876.

# $\chi^2$ -distribution

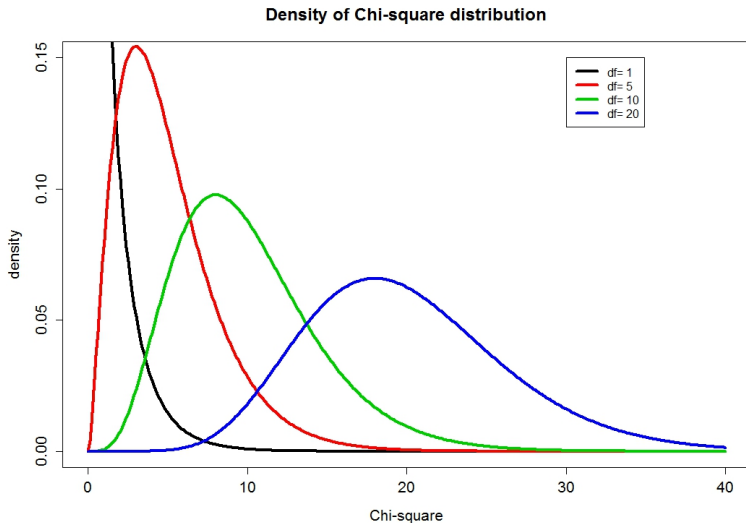
Mean and variance of a  $\chi^2(d)$  is

$$E(Y) = d, \quad \text{Var}(Y) = 2d.$$

The density function has maximum for  $y = 0$ , unless  $d \geq 3$ .



# Examples of $\chi^2$ -distributions



## Estimating the variance in the normal distribution with unknown mean

Suppose  $X_1, \dots, X_n$  is a sample from  $\mathcal{N}(\mu, \sigma^2)$ , where both  $\mu$  and  $\sigma$  is unknown.

From the sample we want to derive an estimate of  $\sigma$ .

- The error on the  $i$ 'th measurement is  $e_i = x_i - \mu$

But we don't know  $\mu$  and insert our best guess:  $\bar{x}$ , to estimate the error:

- $\hat{e}_i = x_i - \bar{x}$

As  $\sigma^2$  is the average squared error we use the estimate

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n \hat{e}_i^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

When we substitute  $\mu$  by  $\bar{x}$ , we divide by  $n-1$  instead of  $n$ , which is sensible since this estimator of  $\sigma^2$  is both unbiased and efficient.

# Distribution of variance estimate when mean is unknown

When we estimate the mean by  $\bar{x}$  it can be shown that

- $\frac{(n-1)S^2}{\sigma^2}$  has a chi-square distribution with  $n - 1$  degrees of freedom.
- In the actual set-up, we have one unknown: the mean of the sample.
- In surveying language, this means that we have  $n - 1$  redundants, when we consider it as a general adjustment.
- And the posterior variance then has  $n - 1$  degrees of freedom (Helmert).

## Example

We have measured the difference in height between A and B 3 times (in mm) and have observed:  $x_1 = 119, x_2 = 112, x_3 = 114$ .

The estimated mean is  $\bar{x} = 115$ . Sum of squared errors

$$sse = (119 - 115)^2 + (112 - 115)^2 + (114 - 115)^2 = 26$$

Unbiased estimate of  $\sigma^2$

- $s^2 = \frac{26}{3-1} = 13mm^2$

Corresponding estimate of the standard deviation

- $s = \sqrt{13} = 3.61mm$